A Solution to Optimal Power Flow Problem using Artificial Bee Colony Algorithm Incorporating FACTS device

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Abstract : This paper presents an intelligent foraging behaviour based optimization approach i.e. artificial bee colony (ABC) algorithm for achieving the optimal power flow (OPF) problem solution incorporating the flexible alternating current transmission system (FACTS) device which is static synchronous series compensator (SSSC). The SSSC consists of a solid-state voltage source converter with gate turn off (GTO) device, a dc link capacitor, a magnetic circuit and a controller. The injected voltage is in quadrature with the line current and emulates an inductive or a capacitive reactance so as to influence the power flow in the transmission lines. The effectiveness of the approach has been tested on IEEE 14-bus system with and without SSSC. Results show that the ABC algorithm gives better solution to enhance the system performance with SSSC compared to without SSSC.

Keywords: Artificial Bee Colony Algorithm, Foraging Behaviour, Optimal Power Flow, Power Loss, SSSC.

I. INTRODUCTION

The electric power industry over the worldwide becoming complex day to day and continuous requirements are coming for stable, secured, controlled, economic and better quality power. These requirements become more essential when environment becoming more vital and important deregulation. Power transfer capacity in transmission system is limited due to various factors such as steady state stability limit, thermal limit, transient stability limit and system damping or even negative damping. The transmission system become increasingly subject several constraints and difficulties to operate. To meet these requirements number of applications linked with FACTS devices has been increased in recent years. A.Edris et.al. [1] defined FACTS is a system composed of static equipment used for the AC transmission of electrical energy. It is meant to enhance controllability and increase power transfer capability of the network. It is generally a power electronics based system. FACTS technology [2] provides feasible and cost-effective solution to these problems and these devices are required to use worldwide for improving performance of power system [3].

Recently, several FACTS devices have been implemented and installed in practical power systems such as static VAR compensator (SVC), thyristor controlled series capacitor (TCSC), and thyristor controlled phase shifter (TCPS) [4]. Some FACTS devices which operates based on the synchronous voltage source (SVS) include the SSSC [5] and the unified power flow controller (UPFC) [6]. The SSSC provides a compensating voltage over both a capacitive and inductive range irrespective of the line current. The magnitude and phase of this inserted ac compensating voltage can be rapidly adjusted by SSSC controls.

Several population-based methods have been proposed for solving the OPF problem successfully such as evolutionary algorithms [7] and swarm intelligence-based algorithms [8]. Although genetic algorithm (GA) [9], genetic programming (GP) [10], evolution strategy (ES) and evolutionary programming (EP) [11] are popular evolutionary algorithms, GA is the most widely used one in the literature. GA is based on genetic science and natural selection and it attempts to simulate the phenomenon of natural evolution at genotype level while ES and EP simulate the phenomenon of natural evolution at phenotype level. One of the evolutionary algorithms which have been introduced recently is differential evolution (DE) algorithm. A popular swarmintelligence-based algorithm is the particle swarm optimization (PSO) algorithm which was introduced by Eberhart and Kennedy in 1995 [12]. A.V.Naresh Babu and S.Sivanagaraju [13] proposed a new approach based on two step initialization to solve the OPF problem. Methods to find the solution for OPF problem have been discussed in [14, 15]. The ABC algorithm [16, 17] is a new metaheuristic, population-based optimization technique inspired by the intelligent foraging behavior of the honeybee swarm. The OPF problem was formulated as an optimization problem and solved using ABC algorithm. The objective function is to minimize the fuel cost. A load flow model is used i.e. newton-rapson (NR) method. This model is further modified to incorporate SSSC into the network and ABC technique is applied to the model to enhance the performance of the power system. The effectiveness of the method was tested on standard IEEE 14-bus test system and the results are presented.

II. STATIC SYNCHRONOUS SERIES COMPENSATOR

The voltage source converter based series compensator, called static synchronous series compensator was proposed by Gyugyi in 1989. An SSSC comprises of voltage source converter, capacitor and a coupling transformer that is used to insert the ac output voltage of the inverter in series with the transmission line. This is equivalent to providing controllable capacitive or inductive reactance compensation independent of the line current. The magnitude and phase of this inserted ac compensating voltage can be rapidly adjusted by the SSSC controls [18]. The VSC is triggered by the SSSC control which itself receives setpoint values. The VSC is protected against unacceptable high fault currents by a mechanical bypass which can be closed if necessary. In this way, the SSSC controls the power flow of the transmission line or the voltage of the bus.



Fig. 1 Schematic diagram of SSSC

III. MATHEMATICAL FORMULATION OF OPF WITH SSSC

Mathematically, the OPF problem with FACTS to minimize fuel cost generation is solved by maintaining thermal and voltage constraints can be formulated as follows

Minimize
$$\sum_{l=1}^{xgen} (a_l P_{genl}^2 + b_l P_{genl} + c_l) \ \$/h \tag{1}$$

where a_l , b_l , c_l are cost co-efficient of generator at bus l

xgen is the number of generator buses.

Power flow equalities in the optimal power flow are given as follows

$$Pgen_{l} - Pdem_{l} - \sum_{m=1}^{xb} |V_{l}| |V_{m}| |Y_{lm}| \cos(\theta_{lm} - \delta_{l} + \delta_{m}) + P_{inj,n} = 0$$
(2)

$$Qgen_{l} - Qdem_{l} + \sum_{m=1}^{xb} |V_{l}| |V_{m}| |Y_{lm}| \sin(\theta_{lm} - \delta_{l} + \delta_{m}) + Q_{inj,n} = 0$$
(3)

 $Pgen_l$ and $Qgen_l$ is the active and reactive power of generation at bus l,

 $Pdem_l$ and $Qdem_l$ is the active and reactive load demand at the same bus, and elements of the bus admittance matrix are represented by Y_{lm} and θ_{lm} is the angle difference of transmission line connected between l & m buses.

Active power outputs, reactive power outputs, and generation bus voltages are restricted by their lower and upper limits and the generator constraints are given as follows

$$Pgen_l^{\min} \le Pgen_l \le Pgen_l^{\max} \qquad l = 1, 2, 3, ..., xgen$$
(4)

$$Qgen_l^{\min} \le Qgen_l \le Qgen_l^{\max} \qquad l = 1, 2, 3, ..., xgen$$
⁽⁵⁾

$$V_l^{\min} \le V_l \le V_l^{\max}$$
 $l = 1, 2, 3, ..., xb$ (6)

xb is the number of buses

Transformer tap settings are restricted by their lower and upper limits and the transformer constraints are given as follows

$$T_l^{\min} \le T_l \le T_l^{\max}$$
 $l = 1, 2, 3, ..., xt$ (7)

xt is the number of transformers.

Shunt VAR compensations due to capacitor banks are restricted by their limits and the shunt VAR constraints are given as follows

$$Q \operatorname{var}_{l}^{\min} \leq Q \operatorname{var}_{l} \leq Q \operatorname{var}_{l}^{\max} \qquad l = 1, 2, 3, ..., x \operatorname{var}$$
(8)

x var is the number of shunt VAR compensators. SSSC device constraints are restricted by their limits as follows

 $Vser^{\min} \leq Vser \leq Vser^{\max}$

$$\theta ser^{\min} \le \theta ser \le \theta ser^{\max} \tag{10}$$

Vser and θ ser are the Series voltage source magnitude and Series voltage source angle respectively. The load of l^{th} transmission line is restricted by its limits are given as follows

$$S_{tl} \le S_{tl}^{\max}$$
 $tl = 1, 2, 3, ..., xtl$ (11)

xtl is the number of transmission lines.

IV. ARTIFICIAL BEE COLONY ALGORITHM

The Artificial Bee Colony algorithm proposed by Dervis Karaboga in 2005 for real-parameter optimization is a recently introduced optimization algorithm which simulates the foraging behaviour of bee colony. In the ABC algorithm, the foraging artificial bees are divided into three groups: employed bees, unemployed bees and scout bees. One half of the colony size of the ABC algorithm represents the number of employed bees, and the second half stands for the number of unemployed bees. The employed bees are responsible for exploiting the explored food sources and passing their food information to onlooker bees. The onlooker bees will make a move to choose a food source on this information, and then further exploit the foods around the chosen food source. The employed bee change to a scout bee when it abandons a food source and search the environment surrounding the nest (up to a 14 km radius) for the new food sources. The details of the algorithm are as follows

4.1 Food source sites initialization

In the initialization of the algorithm, a set of food source sites (eb) are created randomly. Let's consider u^{th} food source in the population as

$$d_{u} = d_{u,1}, d_{u,2}, d_{u,3}, \dots, d_{u,n}$$
(12)

And each food source site is created as per the Eq. (13)

$$d_{u,v} = d_u^{\min} + rand(0,1)(d_u^{\max} - d_u^{\min})$$
(13)

Where u signifies the size of food source sites, u=1, 2, 3... eb, v signifies the parameters to be optimized,

v = 1, 2, 3, ..., ncv, $d_u^{\text{max}} \& d_u^{\text{min}}$ are the upper and lower bounds for the dimension *u*. After initialization of the food source sites fit_u amounts are calculated.

4.2. Employed bee forager

A new candidate food sources is created by modification of d_u of its current position and then calculate nectar or fit_u amount. The position of the new food source is defined as

$$w_{u,v} = d_{u,v} + \xi_{u,v} (d_{u,v} - d_{q,v})$$
(14)

Where q = 1, 2, 3, ..., eb is a randomly chosen index that has to be different from $u, \xi_{u,v}$ is a uniformly distributed real random number in the range [-1, 1].

$$fit_{u} = \begin{cases} \frac{1}{1 + obj_{u}} & \text{if } obj_{u} \ge 0\\ 1 + abs(obj_{u}) & \text{if } obj_{u} < 0 \end{cases}$$
(15)

Where obj_u is the cost value or objective value of the solution w_u . If the fit_u of w_u is equal or better than that of d_u , it will be replaced by the new candidate food source position w_u , otherwise the previous position is kept in memory.

4.3 Onlooker probabilities

After all employed bees complete the search process, each onlooker bee chooses a food source. The probability that a food source will be chosen by the onlooker bee is calculated by the following expression

$$brob_{u} = \frac{fit_{u}}{\sum_{u=1}^{eb} fit_{u}}$$
(16)

4.4 Onlooker bee forager

This is also similar to employed bee forager step. Here, candidate food source is created of its current position as per Eq. (14) and calculate fit_u value. If the new candidate food source has equal or better fit_u value than the old source, it is replaced with the old one in the memory. Otherwise, the old one is retained in the memory. This process is repeated until all onlookers are distributed onto food source sites.

4.5 Scout bee forager

If the fit_u value of the employed bees does not improved by a continuous predetermined number of iterations, those food sources are abandoned. The food source abandoned by its bee is replaced with a new food source discovered by the scout as per Eq. (13)

V. RESULTS AND DISCUSSIONS

Simulation studies are carried out in this section to investigate the effects of the SSSC on the power system. The method is implemented using MATLAB software package on a personal computer with Intel Pentium dual core 2.6 GHz processor and 2 GB RAM. The ABC algorithm is employed to solve OPF problem by incorporating SSSC for enhancement of system performance. The ABC parameters used for the simulation are summarized in Table 1.

Table 1 ABC parameters				
S.No	Control variables of ABC algorithm	values		
1	Swarm size	20		
2	Number of employed bees foragers	50% of swarm size		
3	Number of onlooker bees foragers	50% of swarm size		
4	Number of iterations	10		
5	Number of scouts per cycle	1		

Table 1 ABC parameters

Table 2 Optimal settings of control variables for IEEE-14 Bus test system

S.No	Parameters	Case 1	Case 2
1	P _{g1}	74.015	82.213
2	P_{g2}	113.467	93.966
3	P _{g3}	27.634	36.403
4	P_{g6}	37.317	40.109
5	P_{g8}	11.448	10.963
6	V_{g1}	1.050	1.064
7	V_{g2}	1.037	1.058
8	V_{g3}	1.023	1.018
9	V_{g6}	0.995	1.023
10	V_{g8}	1.023	1.024
11	Τ ₁	1.007	1.002
12	Τ ₂	0.918	0.926
13	Τ ₃	1.037	0.994
14	Q _{C1}	2.63	3.274
15	Total real power generation	263.881	263.654
16	Total Cost	927.300	917.392
17	Real power loss	4.881	4.654
18	V _{se} (p.u)		0.095
19	$\theta_{se}(deg)$		91.312

Table 3 Bus voltages of IEEE-14 Bus system

	Case 1		Case 2	
Bus No.	Voltage magnitude (p.u)	Voltage angle (deg.)	Voltage magnitude (p.u)	Voltage angle (deg.)
1	1.050	0.000	1.064	0.000
2	1.037	-1.341	1.058	-1.131
3	1.023	-6.568	1.018	-6.437
4	1.001	-5.104	1.026	-5.004

5	1.016	-4.048	1.038	-4.062
6	0.995	-5.735	1.023	-6.062
7	1.005	-6.801	1.015	-6.644
8	1.023	-5.725	1.024	-5.532
9	0.993	-8.399	1.007	-8.225
10	0.985	-8.268	1.002	-8.158
11	0.986	-7.178	1.008	-7.094
12	0.979	-6.850	1.008	-7.094
13	0.974	-7.081	1.002	-7.280
14	0.969	-8 959	0.986	-8.917

The network and load data for this system is taken from [19]. To test the ability of the ABC algorithm one objective function is considered that is minimization of cost of generation. In order to show the effect of power flow control capability of the SSSC in ABC OPF algorithm, two case studies are carried out on the standard IEEE 14-bus system.

Case 1: OPF without SSSC,

Case 2: OPF with SSSC.



Fig. 2 Cost vs. iterations of IEEE 14 bus system

From the Table 2 and Table 3, it can be seen that the installation of SSSC in the network gives the good performance of the system in terms of reduction in cost of generation, power loss reduction and better voltages. It also gives that ABC algorithm is able to enhance the system performance while maintaining all control variables and reactive power outputs within their limits. The convergence characteristics with and without SSSC by using ABC algorithm is shown in Fig 2. From the characteristics it can be seen that the convergence tendency is better with SSSC compared to without SSSC.

VI. CONCLUSION

This paper incorporates the SSSC in OPF problem to minimize the fuel cost of generation and enhance the system performance. The ABC algorithm is used for solving the OPF problem. The OPF problem is formulated as a nonlinear optimization problem with equality and inequality constraints. The results of the ABC algorithm were compared with and without SSSC. Among the two test cases, test case 2 had the less fuel cost of generation, power loss reduction as well as voltage improvements. The convergence tendency of the ABC algorithm shows that the algorithm relatively converges in less number of cycles.

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