A study on Ricci soliton in *s*-manifolds.

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Abstract: In this paper, we study semi symmetric and pseudo symmetric conditions in S-manifolds, those are $R \cdot R = 0$, $R \cdot C = 0$, $C \cdot R = 0$, $C \cdot C = 0$, $R \cdot R = L_1 Q(g, R)$, $R \cdot C = L_2 Q(g, C)$, $C \cdot R = L_3 Q(g, R)$, and $C \cdot C = L_4 Q(g, C)$, where C is the Concircular curvature tensor and L_1, L_2, L_3, L_4 are the smooth functions on M, further we discuss about Ricci soliton. Keywords: S-manifold, η -Einstein manifold, Einstein manifold, Ricci soliton.

I. Introduction

The notion of f-structure on a (2n+s)-dimensional manifold M, i.e., a tensor field of type (1,1)on M of rank 2n satisfying $f^3 + f = 0$, was firstly introduced in 1963 by K. Yano [28] as a generalization of both (almost) contact (for s = 1) and (almost) complex structures (for s = 0). During the subsequent years, this notion has been furtherly developed by several authors [3], [4], [11], [12], [15], [16], [17]. Among them, H. Nakagawa in [16] and [17] introduced the notion of framed f-manifold, later developed and studied by S.I. Goldberg and K. Yano ([11], [12]) and others with the denomination of globally framed f-manifolds.

A Riemannian manifold M is called locally symmetric if its curvature tensor R is parallel, i.e., $\nabla R = 0$, where ∇ denotes the Levi-Civita connection. As a generalization of locally symmetric manifolds the notion of semisymmetric manifolds was defined by

 $(R(X,Y) \cdot R)(U,V)W = 0, X,Y,U,V,W \in TM$

and studied by many authors [18], [19], [26], [20]. Z.I. Szabo [25] gave a full intrinsic classification of these spaces. R. Deszcz [8, 9] weakened the notion of semisymmetry and introduced the notion of pseudosymmetric manifolds by

 $(R(X,Y)\cdot R)(U,V)W = L_R[((X \wedge Y)\cdot R)(U,V)W], \quad (1.1)$

where L_R is smooth function on M and $X \wedge Y$ is an endomorphism defined by

$$(X \wedge Y)Z = g(Y,Z)X - g(X,Z)Y. \quad (1.2)$$

Definition 1 A Ricci soliton is a natural generalization of an Einstein metric and is defined on a Riemannian manifold (M, g). A Ricci soliton is a triple (g, V, λ) with g is a Riemannian metric, V is a vector field and λ is a real scalar such that

 $(L_V)g(X,Y) + 2S(X,Y) + 2\lambda g(X,Y) = 0.$ (1.3)

where S is a Ricci tensor of M and L_V denotes the Lie derivative operator along the vector field V

. The Ricci soliton is said to be shrinking, steady and expanding according as λ is negative, zero and positive respectively. The authors R.Sharma [22, 23, 24] and M.M.Tripathi [27] initiated the study of Ricci solitons in contact manifold. But $C\bar{\alpha}lin$ and Crasmareanu [6], Bagewadi and Ingalahalli [14, 1], S.Debnath and A.Battacharya [7] have studied the existence and also obtained results on Ricci solitons in f-kenmotsu manifolds, α -Sasakian manifolds, Lorentzian α -Sasakian manifolds, Trans-Sasakian manifolds using L.P.Eisenhart problem [10]. But C.S.Bagewadi, Ingalahalli and Ashok, C.S.Bagewadi and K.R.Vidyavathi have studied Ricci solitons in Kenmotsu manifolds, almost $C(\alpha)$ manifolds using semi-symmetric and pseudosymmetric conditions [2]. In the present paper, we study Ricci soliton in S-manifolds satisfying semi symmetric and pseudo symmetric conditions those are $R \cdot R = 0$, $R \cdot C = 0$, $C \cdot R = 0$, $C \cdot C = 0$, $R \cdot R = L_1Q(g, R)$, $R \cdot C = L_2Q(g, C)$, $C \cdot R = L_3Q(g, R)$, and $C \cdot C = L_4Q(g, C)$, where C is the

Concircular curvature tensor and L_1, L_2, L_3, L_4 are the smooth functions on M.

II. Preliminaries

Let M be a (2n+s)-dimensional manifold with an f-structure of rank 2n. If there exists global vector fields $\xi_{\alpha}, \alpha = (1, 2, 3, ..., s)$ on M such that;

$$f^{2} = -I + \sum \xi_{\alpha} \otimes \eta_{\alpha}, \quad \eta_{\alpha}(\xi_{\beta}) = \delta^{\alpha}_{\beta}, \quad (2.1)$$

$$f\xi_{\alpha} = 0, \quad \eta_{\alpha} \circ f = 0, \quad (2.2)$$

$$g(X, \xi_{\alpha}) = \eta_{\alpha}(X), \quad g(X, fY) = -g(fX, Y), \quad (2.3)$$

where η_{α} are the dual 1-forms of ξ_{α} , we say that the f-structure has complemented frames. For such a manifold there exists a Riemannian metric g such that

$$g(X,Y) = g(fX, fY) + \sum \eta_{\alpha}(X)\eta_{\alpha}(Y)$$
(2.4)

for any vector fields X and Y on M.

An f-structure f is normal, if it has complemented frames and

$$[f,f]+2\sum\xi_{\alpha}\otimes d\eta_{\alpha}=0,$$

where [f, f] is Nijenhuis torsion of f.

Let *F* be the fundamental 2-form defined by $F(X,Y) = g(X, fY), X, Y \in T(M)$. A normal *f*-structure for which the fundamental form *F* is closed, $\eta_1 \wedge, \dots, \eta_s \wedge (d\eta_\alpha)^n \neq 0$ for any α , and $d\eta_1 = \dots = d\eta_s = F$ is called to be an *S*-structure. A smooth manifold endowed with an *S*-stucture will be called an *S*-manifold. These manifolds introduced by Blair [3].

We have to remark that if we take s = 1, S -manifolds are natural generalizations of Sasakian manifolds. In the case $s \ge 2$ some interesting examples are given [3], [13].

If M is an S-manifold, then the following relations holds true [3];

$$\nabla_{X}\xi_{\alpha} = -fX, \quad X \in T(M), \alpha = 1, 2, \dots, s \quad (2.5)$$
$$(\nabla_{X}f)Y = \sum \{g(fX, fY)\xi_{\alpha} + \eta_{\alpha}(Y)f^{2}X\}, \quad X, Y \in T(M), \quad (2.6)$$

where ∇ is the Riemannian connection of g. Let Ω be the distribution determined by the projection tensor f^2 and let N be the complementry distribution which is determined by $f^2 + I$ and spanned by ξ_1, \ldots, ξ_s . It is clear that if $X \in \Omega$ then $\eta_{\alpha}(X) = 0$ for any α , and if $X \in N$, then fX = 0. A plane section π on M is called an invariant f-section if it is determined by a vector $X \in \Omega(x), x \in M$, such that $\{X, fX\}$ is an orthonormal pair spanning the section. The sectional curvature of π is called the f-sectional curvature. If M is an S-manifold of constant f-sectional curvature k, then its curvature tensor has the form

$$R(X,Y,Z,W) = \sum_{\alpha,\beta} \{g(fX,fW)\eta_{\alpha}(Y)\eta_{\beta}(Z) - g(fX,fZ)\eta_{\alpha}(Y)\eta_{\beta}(W) + g(fY,fZ)\eta_{\alpha}(X)\eta_{\beta}(W) - g(fY,fW)\eta_{\alpha}(X)\eta_{\beta}(Z)\} + \frac{1}{4}(k+3s)\{g(fX,fW)g(fY,fZ) - g(fX,fZ)g(fY,fW)\} + \frac{1}{4}(k-s)\{F(X,W)F(Y,Z) - F(X,Z)F(Y,W) - 2F(X,Y)F(Z,W)\},$$
(2.7)

where $X, Y, Z, W \in T(M)$. Such a manifold N(K) will be called an S-space form. The Euclidean space E^{2n+s} and the hiperbolic space H^{2n+s} are examples of S-space forms.

Definition 2 *S*-manifold $(M, f, \eta_{\alpha}, g, \xi_{\alpha})$ is said to be η -Einstein if the Ricci tensor *S* of *M* is of the form

$$S = ag + b \sum_{\alpha=1}^{s} \eta_{\alpha} \otimes \eta_{\alpha},$$

where a, b are constants on M.

Now contracting equation (2.7) we get

$$S(Y,Z) = \left[\frac{4s + (k+3s)(2n-1) + 3(k-s)}{4}\right]g(Y,Z) + \left[\frac{(2n+s-2)(4-k-3s) - 3(k-s)}{4}\right]\sum_{\alpha} \eta_{\alpha}(Y)\eta_{\alpha}(Z), \quad (2.8)$$

 $S(Y,\xi_{\alpha}) = \frac{1}{4} [s^{2}(13-6n-k-3s)+2s(7n-5)+k(2-s)+2nk(1-s)].$ (2.9) From (2.7) we have

From (2.7) we have

$$R(X,Y)\xi_{\alpha} = s\sum_{\alpha} \{\eta_{\alpha}(Y)X - \eta_{\alpha}(X)Y\}, \qquad (2.10)$$

$$R(\xi_{\alpha},Y)Z = s\sum_{\alpha} \{g(Y,Z)\xi_{\alpha} - \eta_{\alpha}(Z)Y\}, \qquad (2.11)$$

$$\eta_{\alpha}(R(X,Y)Z) = s\sum_{\alpha} \{g(Y,Z)\eta_{\alpha}(X) - g(X,Z)\eta_{\alpha}(Y)\}. \qquad (2.12)$$

III. Ricci Soliton In Semi-Symmetric S - Manifolds

An *S*-manifold is said to be semi-symmetric if $R \cdot R = 0$. $(R(\xi_{\alpha}, Y) \cdot R)(U, V)W = 0,$ (3.1)

$$R(\xi_{\alpha}, Y)R(U, V)W - R(R(\xi_{\alpha}, Y)U, V)W - R(U, R(\xi_{\alpha}, Y)V)W - R(U, V)R(\xi_{\alpha}, Y)W = 0.$$
(3.2)
Using (2.11) in (3.2), we get
$$s\sum_{\alpha} \{g(Y, R(U, V)W)\xi_{\alpha} - \eta_{\alpha}(R(U, V)W)Y - g(Y, U)R(\xi_{\alpha}, V)W + \eta_{\alpha}(U)R(Y, V)W - g(Y, V)R(U, \xi_{\alpha})W + \eta_{\alpha}(V)R(U, Y)W - g(Y, W)R(U, V)\xi_{\alpha} + \eta_{\alpha}(W)R(U, V)Y\} = 0$$
(3.3)

By taking an inner product with ξ_{α} then we get

$$\sum_{\alpha} \{ sR(U,V,W,Y) - \eta_{\alpha}(R(U,V)W)\eta_{\alpha}(Y) - g(Y,U)\eta_{\alpha}(R(\xi_{\alpha},V)W) + \eta_{\alpha}(U)\eta_{\alpha}(R(Y,V)W) \}$$

 $-g(Y,V)\eta_{\alpha}(R(U,\xi_{\alpha})W) + \eta_{\alpha}(V)\eta_{\alpha}(R(U,Y)W) - g(Y,W)\eta_{\alpha}(R(U,V)\xi_{\alpha}) + \eta_{\alpha}(W)\eta_{\alpha}(R(U,V)Y)\} = 0.$ (3.4)

By using (2.10), (2.12) in (3.4) we have

$$sR(U,V,W,Y) + s^2g(Y,V)g(U,W) - s^2g(Y,U)g(V,W) = 0. (3.5)$$

Taking $U = Y = e_i$ in (3.5) and summing over $i = 1, 2, \dots, 2n + s$ we get

$$f(V,W) = s(2n+s-1)g(V,W)$$
 (3.6)

Thus we state the following;

S

Theorem 1 Semi symmetric *S* -manifold is an Einstein manifold.

If V is co-linear with ξ , then Ricci soliton along ξ is given by

 $(L_{\varepsilon}g)(X,Y) + 2S(X,Y) + 2\lambda g(X,Y)$

Definition 3 Let $(f, \xi_1, \xi_2, \dots, \xi_s, \eta_1, \eta_2, \dots, \eta_s, g)$ is the contact *S*-frame manifold, if *V* is in the linear span (combination) of $\xi_1, \xi_2, \dots, \xi_s$ then $V = c_1\xi_1 + c_2\xi_2 + \dots + c_s\xi_s$ and the Ricci soliton is a

triple $(g, \xi_{\alpha}, \lambda)$ with g is a Riemannian metric, $\xi_{\alpha}, (\alpha = 1, 2, ..., s)$ is a vector field and λ is a real scalar such that

$$\left(\sum_{i=1}^{s} c_{i} L_{\xi_{i}} g\right)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) = 0$$
(3.7)

From (3.7) we have

 $c_i g(\nabla_X \xi_\alpha, Y) + c_i g(\nabla_Y \xi_\alpha, X) + 2S(X, Y) + 2\lambda g(X, Y) = 0.$ (3.8) Using (2.5) in (3.8) we get

$$c_i g(-fX,Y) + c_i g(-fY,X) + 2S(X,Y) + 2\lambda g(X,Y) = 0$$
 (3.9)
From (3.6) and (3.9) we have

 $(s(2n+s-1)+\lambda)g(X,Y) = 0$ (3.10)

Taking $X = Y = e_i$ in (3.10) and summing over $i = 1, 2, \dots, 2n + s$, we get the value of λ $\lambda = -s(2n + s - 1)(<0)$

Thus we state the following;

Theorem 2 Ricci soliton in semi-symmetric S -manifold is shrinking.

Corollary 1 Ricci soliton in semi symmetric S-manifold is steady if s = 0 (Kaehler manifold) and is shrinking if s = 1 (Sasakian manifold).

IV. Ricci soliton in *S* -manifolds satisfying $R \cdot C = 0$.

The Concircular curvature tensor C is given by

$$C(X,Y)Z = R(X,Y)Z - \frac{r}{2n(2n+1)} \{g(Y,Z)X - g(X,Z)Y\}$$
(4.1)

Using (2.10), (2.11) and (2.12) in (4.1) we get

$$C(X,Y)\xi_{\alpha} = \left[s - \frac{r}{2n(2n+1)}\right]_{\alpha} \left[X\eta_{\alpha}(Y) - \eta_{\alpha}(X)Y\right], \quad (4.2)$$

$$C(\xi_{\alpha}, Y)Z = \left[s - \frac{r}{2n(2n+1)}\right]_{\alpha} \{g(Y, Z)\xi_{\alpha} - Y\eta_{\alpha}(Z)\}, \qquad (4.3)$$

$$\eta_{\alpha}(C(X, Y)Z) = \left[s - \frac{r}{2n(2n+1)}\right]_{\alpha} \{g(Y, Z)\eta_{\alpha}(X) - g(X, Z)\eta_{\alpha}(Y)\}. \qquad (4.4)$$

Let us assume that the condition $R((\xi_{\alpha},Y)\cdot C)(U,V)W=0$ hold on M , then

$$R(\xi_{\alpha}, Y)C(U, V)W - C(R(\xi_{\alpha}, Y)U, V)W - C(U, R(\xi_{\alpha}, Y)V)W - C(U, V)R(\xi_{\alpha}, Y)W = 0.$$
(4.5)

Using (2.11) in (4.5), we get

$$s\sum_{\alpha} \{g(Y, C(U, V)W)\xi_{\alpha} - \eta_{\alpha}(C(U, V)W)Y - g(Y, U)C(\xi_{\alpha}, V)W + \eta_{\alpha}(U)C(Y, V)W - g(Y, V)C(U, V)\xi_{\alpha} + \eta_{\alpha}(W)C(U, V)Y\} = 0$$
(4.6)

By taking an inner product with ξ_{α} then we get

$$\sum_{\alpha} \{ sC(U,V,W,Y) - \eta_{\alpha}(C(U,V)W)\eta_{\alpha}(Y) - g(Y,U)\eta_{\alpha}(C(\xi_{\alpha},V)W) + \eta_{\alpha}(U)\eta_{\alpha}(C(Y,V)W) \}$$

$$-g(Y,V)\eta_{\alpha}(C(U,\xi_{\alpha})W) + \eta_{\alpha}(V)\eta_{\alpha}(C(U,Y)W) - g(Y,W)\eta_{\alpha}(C(U,V)\xi_{\alpha}) + \eta_{\alpha}(W)\eta_{\alpha}(C(U,V)Y) = 0.$$
(4.7)
By using (4.2), (4.4) in (4.7) we have

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$$C(U,V,W,Y) = \left[s - \frac{r}{2n(2n+1)}\right] \{g(Y,U)g(V,W) - g(Y,V)g(U,W)\}.$$
 (4.8)

Taking $U = Y = e_i$ in (4.8) and summing over $i = 1, 2, \dots, 2n + s$ and using (4.1) we get

S(V,W) = s(2n+s-1)g(V,W) (4.9)

Thus we state the following;

Theorem 3 *S* -manifold satisfying the condition $R \cdot C = 0$ is an Einstein manifold. From (4.9) and (3.9) we have

$$(s(2n+s-1)+\lambda)g(X,Y) = 0$$
 (4.10)

Taking $X = Y = e_i$ in (4.10) and summing over $i = 1, 2, \dots, 2n + s$, we get the value of λ $\lambda = -s(2n + s - 1)(<0)$

Thus we state the following;

Theorem 4 Ricci soliton in S -manifold satisfying the condition $R \cdot C = 0$ is shrinking.

Corollary 2 Ricci soliton in *S*-manifold satisfying $R \cdot C = 0$ is steady if s = 0 (Kaehler manifold) and is shrinking if s = 1 (Sasakian manifold).

V. Ricci soliton in *S* -manifolds satisfying $C \cdot R = 0$.

Let us assume that the condition $C((\xi_{\alpha}, Y) \cdot R)(U, V)W = 0$ hold on M, then

 $C(\xi_{\alpha}, Y)R(U, V)W - R(C(\xi_{\alpha}, Y)U, V)W - R(U, C(\xi_{\alpha}, Y)V)W - R(U, V)C(\xi_{\alpha}, Y)W = 0.$ (5.1)

Using (4.3) in (5.1), we get

$$\begin{bmatrix} s - \frac{r}{2n(2n+1)} \end{bmatrix}_{\alpha} \{g(Y, R(U, V)W)\xi_{\alpha} - \eta_{\alpha}(R(U, V)W)Y - g(Y, U)R(\xi_{\alpha}, V)W + \eta_{\alpha}(U)R(Y, V)W - g(Y, V)R(U, V)\xi_{\alpha}(U, V)K(U, V)W + \eta_{\alpha}(V)R(U, V)W - g(Y, W)R(U, V)\xi_{\alpha}(U, V)W + \eta_{\alpha}(W)R(U, V)W \} = 0$$
(5.2)

By taking an inner product with ξ_{α} then we get

$$\sum_{\alpha} \{ sR(U,V,W,Y) - \eta_{\alpha}(R(U,V)W)\eta_{\alpha}(Y) - g(Y,U)\eta_{\alpha}(R(\xi_{\alpha},V)W) + \eta_{\alpha}(U)\eta_{\alpha}(R(Y,V)W) \}$$

$$-g(Y,V)\eta_{\alpha}(R(U,\xi_{\alpha})W) + \eta_{\alpha}(V)\eta_{\alpha}(R(U,Y)W) - g(Y,W)\eta_{\alpha}(R(U,V)\xi_{\alpha}) + \eta_{\alpha}(W)\eta_{\alpha}(R(U,V)Y) = 0.$$
(5.3)

By using (4.2), (4.4) in (5.3) we have $R(U,V,W,Y) = s\{g(Y,U)g(V,W) - g(Y,V)g(U,W)\}.$ (5.4)

Taking $U = Y = e_i$ in (5.4) and summing over $i = 1, 2, \dots, 2n + s$ we get

S(V,W) = s(2n+s-1)g(V,W)(5.5)

Thus we state the following;

Theorem 5 *S*-manifold satisfying the condition $C \cdot R = 0$ is an Einstein manifold.

From (5.5) and (3.9) we have

 $(s(2n+s-1)+\lambda)g(X,Y) = 0$ (5.6)

Taking $X = Y = e_i$ in (5.6) and summing over $i = 1, 2, \dots, 2n + s$, we get the value of λ

 $\lambda = -s(2n+s-1)(<0)$

Thus we state the following;

Theorem 6 Ricci soliton in S -manifold satisfying the condition $C \cdot R = 0$ is shrinking.

Corollary 3 Ricci soliton in S -manifold satisfying $C \cdot R = 0$ is steady if s = 0 (Kaehler manifold) and is shrinking if s = 1 (Sasakian manifold).

Ricci soliton in S -manifolds satisfying $C \cdot C = 0$.

Let us assume that the condition $C((\xi_{\alpha}, Y) \cdot C)(U, V)W = 0$ hold on M, then

$$C(\xi_{\alpha}, Y)C(U, V)W - C(C(\xi_{\alpha}, Y)U, V)W - C(U, C(\xi_{\alpha}, Y)V)W - C(U, V)C(\xi_{\alpha}, Y)W = 0.$$
(6.1)
(6.1)
(6.1), we get

Using (4.3) in (6.1), we get

$$\begin{bmatrix} s - \frac{r}{2n(2n+1)} \end{bmatrix}_{\alpha}^{\infty} \{g(Y, C(U, V)W)\xi_{\alpha} - \eta_{\alpha}(C(U, V)W)Y - g(Y, U)C(\xi_{\alpha}, V)W + \eta_{\alpha}(U)C(Y, V)W - g(Y, V)C(U, V)\xi_{\alpha}, V)W + \eta_{\alpha}(V)C(U, V)W - g(Y, W)C(U, V)\xi_{\alpha} + \eta_{\alpha}(W)C(U, V)Y\} = 0$$
(6.2)

By taking an inner product with ξ_{α} then we get

$$\sum_{\alpha} \{ sC(U,V,W,Y) - \eta_{\alpha}(C(U,V)W)\eta_{\alpha}(Y) - g(Y,U)\eta_{\alpha}(C(\xi_{\alpha},V)W) + \eta_{\alpha}(U)\eta_{\alpha}(C(Y,V)W) \}$$

$$-g(Y,V)\eta_{\alpha}(C(U,\xi_{\alpha})W) + \eta_{\alpha}(V)\eta_{\alpha}(C(U,Y)W) - g(Y,W)\eta_{\alpha}(C(U,V)\xi_{\alpha}) + \eta_{\alpha}(W)\eta_{\alpha}(C(U,V)Y) = 0.$$
(6.3)

By using (4.2), (4.4) in (6.3) we have

$$C(U,V,W,Y) = \left[s - \frac{r}{2n(2n+1)}\right] \{g(Y,U)g(V,W) - g(Y,V)g(U,W)\}.$$
 (6.4)

Taking $U = Y = e_i$ in (4.8) and summing over $i = 1, 2, \dots, 2n + s$ and using (4.1) we get

$$S(V,W) = s(2n+s-1)g(V,W)$$
 (6.5)

Thus we state the following;

Theorem 7 S -manifold satisfying the condition $C \cdot C = 0$ is an Einstein manifold.

From (6.5) and (3.9) we have

 $(s(2n+s-1)+\lambda)g(X,Y) = 0$ (6.6)

Taking $X = Y = e_i$ in (6.6) and summing over $i = 1, 2, \dots, 2n + s$, we get the value of λ

$$\lambda = -s(2n+s-1)(<0)$$

Thus we state the following;

Theorem 8 Ricci soliton in S -manifold satisfying the condition $C \cdot C = 0$ is shrinking.

Corollary 4 Ricci soliton in S -manifold satisfying $C \cdot C = 0$ is steady if s = 0 (Kaehler manifold) and is shrinking if s = 1 (Sasakian manifold).

VI. **Ricci soliton in Pseudo-symmetric** S -manifolds

An S-manifold is said to be Pseudo-symmetric if $R \cdot R = L_1 Q(g, R)$.

$$(R(\xi_{\alpha}, Y) \cdot R)(U, V)W = L_{1}[((\xi_{\alpha} \wedge Y) \cdot R)(U, V)W], \quad (7.1)$$

 $R(\xi_{\alpha},Y)R(U,V)W - R(R(\xi_{\alpha},Y)U,V)W - R(U,R(\xi_{\alpha},Y)V)W - R(U,V)R(\xi_{\alpha},Y)W$ $= L_1[(\xi_{\alpha} \wedge Y)R(U,V)W - R((\xi_{\alpha} \wedge Y)U,V)W - R(U,(\xi_{\alpha} \wedge Y)V)W - R(U,V)(\xi_{\alpha} \wedge Y)W]$ (7.2)Using (2.11) L.H.S of (??) is

$$s\sum_{\alpha} \{g(Y, R(U, V)W)\xi_{\alpha} - \eta_{\alpha}(R(U, V)W)Y - g(Y, U)R(\xi_{\alpha}, V)W + \eta_{\alpha}(U)R(Y, V)W - g(Y, V)R(U, \xi_{\alpha})W + \eta_{\alpha}(V)R(U, Y)W - g(Y, W)R(U, V)\xi_{\alpha} + \eta_{\alpha}(W)R(U, V)Y\}.$$
 (7.3)
By taking an inner product with ξ_{α} then we get

$$s\sum_{\alpha} \{ sR(U,V,W,Y) - \eta_{\alpha}(R(U,V)W)\eta_{\alpha}(Y) - g(Y,U)\eta_{\alpha}(R(\xi_{\alpha},V)W) + \eta_{\alpha}(U)\eta_{\alpha}(R(Y,V)W) \}$$

 $-g(Y,V)\eta_{\alpha}(R(U,\xi_{\alpha})W) + \eta_{\alpha}(V)\eta_{\alpha}(R(U,Y)W) - g(Y,W)\eta_{\alpha}(R(U,V)\xi_{\alpha}) + \eta_{\alpha}(W)\eta_{\alpha}(R(U,V)Y)\}.$ (7.4)

By using (2.10), (2.12) in (??) we have

 $s\{sR(U,V,W,Y) + s^2g(Y,V)g(U,W) - s^2g(Y,U)g(V,W)\}.$ (7.5) Again using (2.11) R.H.S of (??), we get

$$L_{1}\left[\sum_{\alpha} \{g(Y, R(U, V)W)\xi_{\alpha} - \eta_{\alpha}(R(U, V)W)Y - g(Y, U)R(\xi_{\alpha}, V)W + \eta_{\alpha}(U)R(Y, V)W - g(Y, V)R(U, \xi_{\alpha}, V)W + \eta_{\alpha}(V)R(U, Y)W - g(Y, W)R(U, V)\xi_{\alpha} + \eta_{\alpha}(W)R(U, V)Y\}\right].$$
 (7.6)

By taking an inner product with ξ_{α} then we get

$$L_{1}\left[\sum_{\alpha} \{sR(U,V,W,Y) - \eta_{\alpha}(R(U,V)W)\eta_{\alpha}(Y) - g(Y,U)\eta_{\alpha}(R(\xi_{\alpha},V)W) + \eta_{\alpha}(U)\eta_{\alpha}(R(Y,V)W)\right]$$

 $-g(Y,V)\eta_{\alpha}(R(U,\xi_{\alpha})W) + \eta_{\alpha}(V)\eta_{\alpha}(R(U,Y)W) - g(Y,W)\eta_{\alpha}(R(U,V)\xi_{\alpha}) + \eta_{\alpha}(W)\eta_{\alpha}(R(U,V)Y)\}].$ (7.7)

By using (2.10), (2.12) in (7.7) we have

 $L_{1}[sR(U,V,W,Y) + s^{2}g(Y,V)g(U,W) - s^{2}g(Y,U)g(V,W)].$ (7.8) From (7.5) and (7.8) we get $[L_{1} - s][sR(U,V,W,Y) + s^{2}g(Y,V)g(U,W) - s^{2}g(Y,U)g(V,W)] = 0.$ (7.9)

$$[L_1 - s][sR(U, V, W, Y) + s^2g(Y, V)g(U, W) - s^2g(Y, U)g(V, W)] = 0.$$
(7.9
refore either $L_n = s$ or

Therefore either $L_1 = s$ or

$$R(U,V,W,Y) = s\{g(Y,U)g(V,W) - g(Y,V)g(U,W)\}.$$
(7.10)

Taking $U = Y = e_i$ in (7.10) and summing over $i = 1, 2, \dots, 2n + s$ we get

$$S(V,W) = s(2n+s-1)g(V,W)$$
(7.11)

Thus we state the following;

Theorem 9 *Pseudo symmetric S -manifold is an Einstein manifold provided* $L_1 \neq s$

From (7.11) and (3.9) we have

 $(s(2n+s-1)+\lambda)g(X,Y) = 0$ (7.12)

Taking $X = Y = e_i$ in (7.12) and summing over $i = 1, 2, \dots, 2n + s$, we get the value of λ

$$\lambda = -s(2n+s-1)(<0)$$

Thus we state the following;

Theorem 10 Ricci soliton in pseudo symmetric S -manifold is shrinking.

Corollary 5 Ricci soliton in pseudo symmetric S -manifold is steady if s = 0 (Kaehler manifold) and is shrinking if s = 1 (Sasakian manifold).

VII. Ricci soliton in *S* -manifolds satisfying $R \cdot C = L_2 Q(g, C)$.

Let us assume that the condition $R((\xi_{\alpha}, Y) \cdot C)(U, V)W = L_2[(\xi_{\alpha} \wedge Y) \cdot C](U, V)W$ hold on M, then

 $R(\xi_{\alpha}, Y)C(U, V)W - C(R(\xi_{\alpha}, Y)U, V)W - C(U, R(\xi_{\alpha}, Y)V)W - C(U, V)R(\xi_{\alpha}, Y)W$ $= L_{2}[(\xi_{\alpha} \wedge Y)C(U, V)W - C((\xi_{\alpha} \wedge Y)U, V)W - C(U, (\xi_{\alpha} \wedge Y)V)W - C(U, V)(\xi_{\alpha} \wedge Y)W]$

(8.1) Using (2.11) L.H.S of (??) is

$$s\sum_{\alpha} \{g(Y, C(U, V)W)\xi_{\alpha} - \eta_{\alpha}(C(U, V)W)Y - g(Y, U)C(\xi_{\alpha}, V)W + \eta_{\alpha}(U)C(Y, V)W - g(Y, V)C(U, \xi_{\alpha}, V)W + \eta_{\alpha}(V)C(U, Y)W - g(Y, W)C(U, V)\xi_{\alpha} + \eta_{\alpha}(W)C(U, V)Y\}.$$
(8.2)

By taking an inner product with ξ_{α} then we get

$$s\sum_{\alpha} \{sC(U,V,W,Y) - \eta_{\alpha}(C(U,V)W)\eta_{\alpha}(Y) - g(Y,U)\eta_{\alpha}(C(\xi_{\alpha},V)W) + \eta_{\alpha}(U)\eta_{\alpha}(C(Y,V)W) - g(Y,V)\eta_{\alpha}(C(U,V)\xi_{\alpha}) + \eta_{\alpha}(W)\eta_{\alpha}(C(U,V)Y)\},$$
(8.3)
By using (4.2), (4.4) in (??) we have

$$s^{2} \left\{ C(U,V,W,Y) - \left[s - \frac{r}{2n(2n+1)}\right] [g(Y,U)g(V,W) - g(Y,V)g(U,W)] \right\}.$$
(8.4)
Again using (2.11) R.H.S of (8.1) is

$$L_{2}\sum_{\alpha} \{g(Y,C(U,V)W)\xi_{\alpha} - \eta_{\alpha}(C(U,V)W)Y - g(Y,U)C(\xi_{\alpha},V)W + \eta_{\alpha}(U)C(Y,V)W - g(Y,V)C(U,\xi_{\alpha})W + \eta_{\alpha}(V)C(U,Y)W - g(Y,W)C(U,V)\xi_{\alpha} + \eta_{\alpha}(W)C(U,V)Y \}.$$
(8.5)

By taking an inner product with ξ_{α} then we get

$$L_{2}\sum_{\alpha} \{sC(U,V,W,Y) - \eta_{\alpha}(C(U,V)W)\eta_{\alpha}(Y) - g(Y,U)\eta_{\alpha}(C(\xi_{\alpha},V)W) + \eta_{\alpha}(U)\eta_{\alpha}(C(Y,V)W)$$

 $-g(Y,V)\eta_{\alpha}(C(U,\xi_{\alpha})W) + \eta_{\alpha}(V)\eta_{\alpha}(C(U,Y)W) - g(Y,W)\eta_{\alpha}(C(U,V)\xi_{\alpha}) + \eta_{\alpha}(W)\eta_{\alpha}(C(U,V)Y)\}.$ (8.6)

By using (4.2), (4.4) in (8.6) we have

$$sL_{2}\left\{C(U,V,W,Y) - \left[s - \frac{r}{2n(2n+1)}\right][g(Y,U)g(V,W) - g(Y,V)g(U,W)]\right\}$$
(8.7)
(8.4) and (8.7) we get

From (8.4) and (8.7) we get

$$[sL_{2}-s^{2}]\left\{C(U,V,W,Y)-\left[s-\frac{r}{2n(2n+1)}\right][g(Y,U)g(V,W)-g(Y,V)g(U,W)]\right\}=0$$
(8.8)

Therefore either $L_2 = s$ or

$$C(U,V,W,Y) = \left[s - \frac{r}{2n(2n+1)}\right] \left[g(Y,U)g(V,W) - g(Y,V)g(U,W)\right]$$
(8.9)

Taking $U = Y = e_i$ in (8.9) and summing over $i = 1, 2, \dots, 2n + s$ we get

$$S(V,W) = s(2n+s-1)g(V,W)$$
 (8.10)

Thus we state the following;

Theorem 11 *S*-manifold satisfying the condition $R \cdot C = L_2Q(g,C)$ is an Einstein manifold provided $L_2 \neq s$.

From (8.10) and (3.9) we have

$$(s(2n+s-1)+\lambda)g(X,Y) = 0$$
 (8.11)

Taking $X = Y = e_i$ in (8.11) and summing over $i = 1, 2, \dots, 2n + s$, we get the value of λ

$$\lambda = -s(2n+s-1)(<0)$$

Thus we state the following;

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Theorem 12 Ricci soliton in S -manifold satisfying the condition $R \cdot C = L_2Q(g, C)$ is shrinking.

Corollary 6 Ricci soliton in S-manifold satisfying $R \cdot C = L_2Q(g,C)$ is steady if s = 0 (Kaehler manifold) and is shrinking if s = 1 (Sasakian manifold).

VIII. Ricci soliton in *S*-manifolds satisfying $C \cdot R = L_3Q(g, R)$. Let us assume that the condition $C((\xi_{\alpha}, Y) \cdot R)(U, V)W = L_3[(\xi_{\alpha} \wedge Y) \cdot R](U, V)W$ hold on *M*, then $C(\xi_{\alpha}, Y)R(U, V)W - R(C(\xi_{\alpha}, Y)U, V)W - R(U, C(\xi_{\alpha}, Y)V)W - R(U, V)C(\xi_{\alpha}, Y)W$ $= L_3[(\xi_{\alpha} \wedge Y)R(U, V)W - R((\xi_{\alpha} \wedge Y)U, V)W - R(U, (\xi_{\alpha} \wedge Y)V)W - R(U, V)(\xi_{\alpha} \wedge Y)W]$ (9.1) Using (5.2), (5.3), (7.6) and (7.7) in (9.1) we get $\left\{ sL_3 - \left[s - \frac{r}{2n(2n+1)} \right] \right\} \{R(U, V, W, Y) - s[g(Y, U)g(V, W) - g(Y, V)g(U, W)]\} = 0$

$$\begin{bmatrix} 3 & 2 \\ 2n(2n+1) \end{bmatrix} \begin{bmatrix} n(0, r, r, r, r) & 3(2(1, 0))g(r, r, r) & g(1, r) g(0, r, r) \end{bmatrix}$$
(9.2)

Therefore, either $L_3 = s - \frac{r}{2n(2n+1)}$ or

$$R(U,V,W,Y) = s\{g(Y,U)g(V,W) - g(Y,V)g(U,W)\}.$$
(9.3)

Taking $U = Y = e_i$ in (9.3) and summing over $i = 1, 2, \dots, 2n + s$ we get

S(V,W) = s(2n+s-1)g(V,W) (9.4)

Thus we state the following;

Theorem 13 *S*-manifold satisfying the condition $C \cdot R = L_3Q(g, R)$ is an Einstein manifold provided

 $L_3 \neq s - \frac{r}{2n(2n+1)}.$

From (9.4) and (3.9) we have

$$(s(2n+s-1)+\lambda)g(X,Y) = 0$$
 (9.5)

Taking $X = Y = e_i$ in (9.5) and summing over $i = 1, 2, \dots, 2n + s$, we get the value of λ

$$\lambda = -s(2n+s-1)(<0)$$

Thus we state the following;

Theorem 14 Ricci soliton in S -manifold satisfying the condition $C \cdot R = L_3Q(g, R)$ is shrinking.

Corollary 7 Ricci soliton in *S*-manifold satisfying $C \cdot R = L_3Q(g,R)$ is steady if s = 0 (Kaehler manifold) and is shrinking if s = 1 (Sasakian manifold).

IX. Ricci soliton in *S* -manifolds satisfying $C \cdot C = L_4 Q(g, C)$.

Let us assume that the condition $C((\xi_{\alpha}, Y) \cdot C)(U, V)W = L_4[(\xi_{\alpha} \wedge Y) \cdot C](U, V)W$ hold on M, then

$$C(\xi_{\alpha}, Y)C(U, V)W - C(C(\xi_{\alpha}, Y)U, V)W - C(U, C(\xi_{\alpha}, Y)V)W - C(U, V)C(\xi_{\alpha}, Y)W$$

= $L_4[(\xi_{\alpha} \wedge Y)C(U, V)W - C((\xi_{\alpha} \wedge Y)U, V)W - C(U, (\xi_{\alpha} \wedge Y)V)W - C(U, V)(\xi_{\alpha} \wedge Y)W]$
(10.1)

Using (6.2), (6.3), (8.5) and (8.6) in (10.1) we get

$$\left\{ sL_4 - \left[s - \frac{r}{2n(2n+1)} \right] \right\} \left\{ C(U,V,W,Y) - \left[s - \frac{r}{2n(2n+1)} \right] \left[g(Y,U)g(V,W) - g(Y,V)g(U,W) \right] \right\} = 0$$
(10.2)

Therefore, either $L_4 = s - \frac{r}{2n(2n+1)}$ or

$$C(U,V,W,Y) = \left[s - \frac{r}{2n(2n+1)}\right] \{g(Y,U)g(V,W) - g(Y,V)g(U,W)\}.$$
 (10.3)

Taking $U = Y = e_i$ in (10.3) and summing over $i = 1, 2, \dots, 2n + s$, using (4.1) we get

$$S(V,W) = s(2n+s-1)g(V,W)$$
(10.4)

Thus we state the following;

Theorem 15 *S*-manifold satisfying the condition $C \cdot C = L_4Q(g, C)$ is an Einstein manifold provided

 $L_4 \neq s - \frac{r}{2n(2n+1)}.$

From (10.4) and (3.9) we have

$$s(2n+s-1)+\lambda)g(X,Y) = 0$$
 (10.5)

Taking $X = Y = e_i$ in (10.5) and summing over $i = 1, 2, \dots, 2n + s$, we get the value of λ

 $\lambda = -s(2n+s-1)(<0)$

Thus we state the following;

Theorem 16 Ricci soliton in S -manifold satisfying the condition $C \cdot C = L_4Q(g,C)$ is shrinking. **Corollary 8** Ricci soliton in S -manifold satisfying $C \cdot C = L_4Q(g,C)$ is steady if s = 0 (Kaehler manifold) and is shrinking if s = 1 (Sasakian manifold).

X. Conclusion

It is shown that Ricci soliton in S-manifold satisfying semi-symmetric and pseudo-symmetric conditions are shrinking. Hence if S = 1, then Sasakian manifolds are shrinking which in accordance with [1], [5], [14], and if S = 0, then Kaehler manifolds are steady [21]

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