

A Review On Designing Of The Dual Reflector Axially Symmetric Cassegrain Antenna

¹Divya Gupta, ²R. A. Deshpande

^{1,2}(Electronics and Telecommunication, K.J.Somaiya College of Engineering, India)

Abstract: Dual reflector antennas are considered as pencil beam antennas that can produce radiation identical to searchlight. Cassegrain Reflector Antenna Design consists of various effects caused by blockage by primary feed or by the subreflector and its effect on overall performance. The objective of the paper is to provide the overview of the designing approach that is used to design the axially symmetric cassegrain antenna. This paper also provides the reader the overview of the various challenges and limitation that are faced by the designer while designing the axially symmetric dual reflector cassegrain system.

Keywords: Cassegrain Antenna, dual reflector design, minimum blockage condition, feed system

I. Introduction

The parabolic reflector antenna is the most preferred antenna system for many applications this is because of its capability of providing higher gain over a wide bandwidth, availability of accurate modeling techniques and design maturity [4]. One of the essential requirements is to achieve very high cross-polarization discrimination over a specified bandwidth, while maintaining the compactness of the overall antenna system [1]. The cross-polarization refers to the radiation of electromagnetic energy into the polarization other than the desired polarization. It can also be considered as the loss of energy in the unintended direction. The presence of high cross-polarization may result in several undesirable effects. It degrades the overall performance of the system and restricts its use for many applications.

The cross-polarization in a reflector type of antenna system depends on many parameters, e. g., the geometry of the reflector, the focal-length to diameter ratio (F/D) of the antenna system, the reflector surface imperfections, support struts, etc. For example, in microwave radiometers, it reduces the beam efficiency and results in poor spatial resolution [2]-[3]. In case of radar, the high cross-polarization can create boresight-jitter (boresight uncertainty). Boresight uncertainty or boresight fluctuations affect the tracking accuracies and result into unsatisfactory operation of the radar. Axially symmetric dual-reflector antennas (Cassegrain or Gregorian, classical or shaped) are of interest in radio astronomy and in Earth-station antenna technology. The design of such systems is often restricted by factors such as mechanical constraints, the type of feed horn used, and the budget of the project [5].

II. Geometry

Consider the geometry of the Cassegrain dual reflector antenna is given in figure1 [5] where D_m and D_s are the diameter of the main reflector and the sub reflector respectively. F is the focal distance of the main reflector, L_m is the distance between the face center of the feed and the apex of the main reflector, L_s is the distance between the apex of the subreflector and the position of the secondary focus. θ_s is the angle between the z axis and the edge ray on the subreflector.

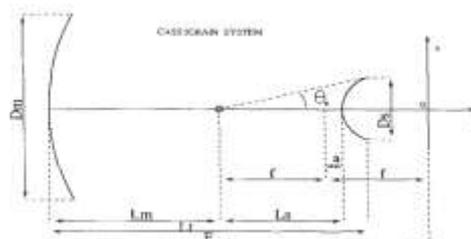


Fig1. Geometry of the Cassegrain Antenna

III. Few Design Tips

- F/D must be taken in between .25 to .85
- $D_s \leq 0.1 D_m$ for $\gg 99\%$ blockage efficiency, as shown in Figure 2[5], and to ensure that the sidelobe levels are not excessive.

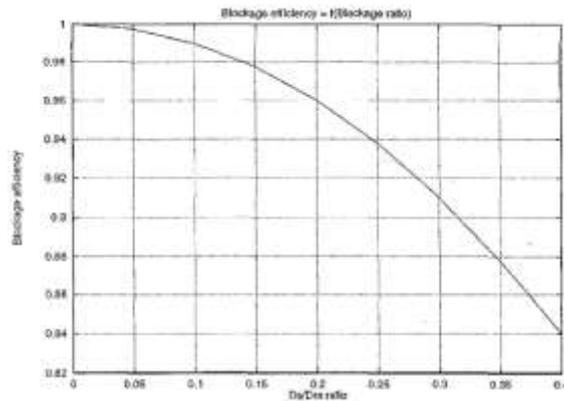


Fig 2. The blockage efficiency as a function of the blockage ratio

- Lm must be chosen keeping in mind the field pattern to be used
- Choose θ_e , to minimize the spillover, i.e., to have an edge illumination on the subreflector of the order of at least -10 to -15 dB.

3.1 Minimum Blockage Condition

If the type of feed to be used is one of the constraints for the antenna design, it is possible to design the antenna to have minimum blockage. In this case, the overall diameter of the feed aperture (including the flange) needs to be known. where D_f represents the overall diameter of the feed (fig 2 [5]).

The condition for minimum blockage (the shadow of the subreflector equals to the shadow of the feed as shown in fig 3as given in Hannan[3]as

$$\frac{F}{2f} = \frac{D_s}{D_f} \tag{1}$$

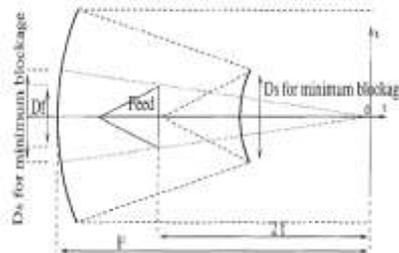


Fig 3. The condition of minimum blockage by subreflector and feed

1.2. Design Parameters

Fig. 1 shows the conventional geometry of axially symmetric Cassegrain antenna. The main reflector is paraboloidal and depends on parameters D_m and F . The subreflector is a convex hyperboloid and depends on parameters D_s , f , and a .

IV. Design Procedure

The design procedure is based on Milligam[6] and Kildal[7].To design the overall geometry six parameters D_m, D_s, F, f, a and θ_e .

Two major problems the designer encounters at the first step are two conceptual defections as illumination loss and spillover loss. If the subreflector is assumed as a virtual feed ,the desired main reflector illumination is as Fig.4a,while virtually the main reflector illumination is as Fig.4b.By overlapping these two figures ,the result is as Fig.4c.In this figure two areas are determined separately as the illumination loss and the spillover loss[8].

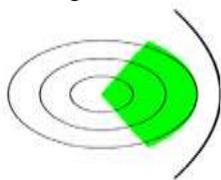


Fig.4a Desired dish Illumination

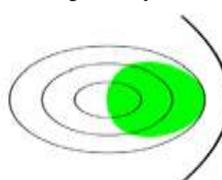


Fig 4b Typical dish illumination

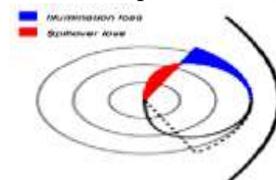


Fig.4c Illumination loss and spillover loss

The starting point is the desired illumination taper between the main reflector and the virtual feed(subreflector).The following procedure is as follows :

4.1 Diameter of the main paraboloidal dish(Dm)

The main reflector illumination taper in Cassegrain antenna is found to be in between 10 db to 15 db [7]. A plot is shown in fig [5].Since the size of the overall antenna system is restricted by the mechanical constraints and the budget of project, the designer must assigns the first mechanical implementation consideration here on D_m according to the prudent antenna size.

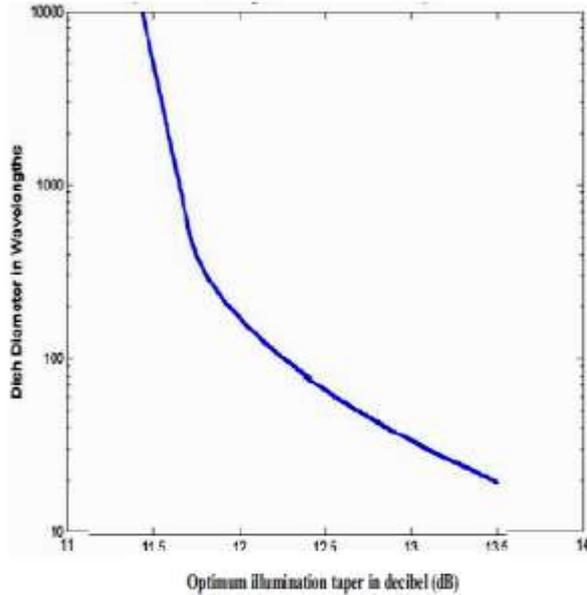


Fig.5 Main reflector diameter Vs. the illumination taper

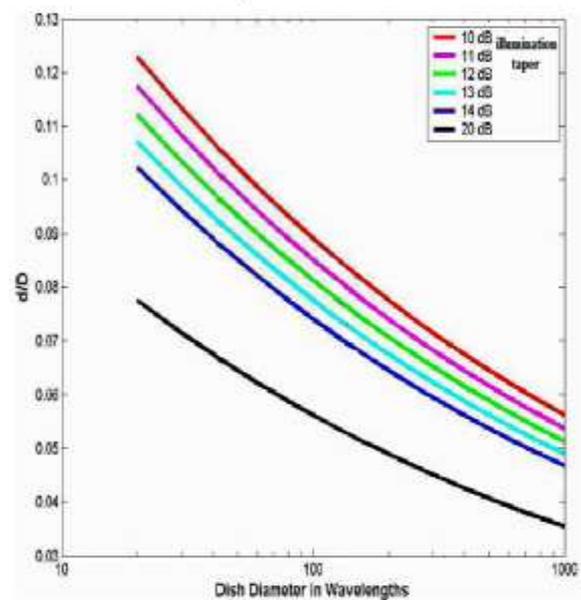


Fig. 6 Ds/Dm vs. main reflector diameter

4.2 Diameter of the hyperboloid subreflector (Ds)

In order to minimize the subreflector blockage, a proposed plot is given in[7] showed in fig.(6) This figure give the optimum ratio of the subreflector diameter to the main reflector diameter.

4.3 Focal distance of the paraboloidal main reflector (F)

The depth of the parabola is given mathematically by equation (2) [9].

$$x = \frac{D^2}{16F} \tag{2}$$

Since F value is inversely proportional to the D_m , appropriate value of the F should be chosen in order to prevent the main reflector from becoming neither deep nor shallow. Thus the second mechanical implementation consideration is defined on the prudent depth for the main reflector. In general antenna have F/ D_m ratios between 0.25 and 0.85[5]

4.4 Focal distance of hyperboloidal subreflector (2f)

From [5], f can be easily calculated by equation(3) after knowing the F, D_s and D_f ,where D_f is the aperture diameter of the feed.

$$f = \frac{FD_f}{2D_s} \tag{3}$$

4.5 Lm, θ_e , Ls and a

L_m, θ_e, L_s and a are achieved in equation (4),(5),(6) and (7) respectively[5].

$$L_m = F - 2f \tag{4}$$

$$L_s = \frac{2D_m f}{D_m - 4F \tan^2(\frac{\theta_e}{2})} \tag{5}$$

$$\theta_e = \text{artan} \left[\frac{8F D_m D_s}{32f F D_m - D_s (16F^2 - D_s^2)} \right] \tag{6}$$

$$a = L_s - f \tag{7}$$

4.6 Eccentricity of the hyperboloid

The eccentricity e , of the hyperboloid is simply given by the equation (8)[5]

$$e = \frac{f}{a} \quad (8)$$

4.7 Feed System Design

In order to minimize the blockage caused by the feed horn's aperture diameter, the following inequality in Equation (9) must be checked [15].

$$D_s > D_f \frac{F}{2f} \quad (9)$$

Now the subreflector must be placed in the far-field (Fraunhofer Region) of the feed horn [10], using equation (10). Placing the subreflector in the reactive near field of the horn will cause to an unexpected radiation pattern, phase error and undesirable antenna performances. Experiments suggest that the distances close to the half of the Fraunhofer distances are likely acceptable without major problems.

$$f > 2 * \frac{D_f^2}{\lambda} \quad (10)$$

V. Conclusion

In this paper, a simple overview of the design approach for Cassegrain Antenna is provided by eight prescribed parameters $D_m, F, D_s, L_m, L_s, \theta_s, f$ and a, D_m, D_s and F Assigned reasonably to fulfil the mechanical implementation constraints.

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