

Common Fixed Point Theorems for Sequence of Mappings in Generalisation of Strict Contractive Conditions

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Abstract: The main purpose of this paper is to obtain fixed point theorems for sequence of mappings in strict contractive conditions which generalizes Theorem 1 of Aamri [1].

Key words and phrases:: Fixed point, Coincidence point, compatible maps, weakly compatible map, non-compatible maps, property (E.A).

I. Introduction

In metric fixed point theory, strict contractive condition do not ensure the existence of common fixed point unless the space is assumed to be compact or the strict condition is replaced by stronger conditions as in [4-6]. In 1986, Jungck [3] proved common fixed point theorem by introducing the notion of compatible mappings. This concept was frequently used to prove the existence theorems in common fixed points of noncompatible mappings and is also very interesting. Work along these lines has recently been initiated by Pant [6, 7]. Section 2 is devoted to definitions and known results which make the paper self reliant. In Section 3 we have proved a common fixed point theorem for sequence of mappings that generalizes the Theorem 2.8 of Aamri [1].

II. Preliminaries

Before proving our results, we need the following definitions and known results in this sequel.

Definition 2.1 ([3]). Let T and S be two self mappings of a metric space (X, d) . T and S are said to be compatible if $\lim_{n \rightarrow \infty} d(ST_{x_n}, TS_{x_n}) = 0$ whenever $\{x_n\}$ is a sequence on X such that $\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n = t$ for some $t \in X$.

Remark 2.2. Two weakly commuting maps are compatible, but the converse is not true as in shown in [3].

Definition 2.3 ([3]). Two self mappings T and S of a metric space X are said to be weakly compatible if $Tu = Su$ for some $u \in X$, then $ST_u = TS_u$.

Note 2.4. Two compatible maps are weakly compatible.

M. Aamri [1] introduced the concept property (E.A) in the following way.

Definition 2.5 (Aamri [1]). Let S and T be two self mappings of a metric space (X, d) . We say that T and S satisfy the property (E.A) if there exists a sequence $\{x_n\}$ such that $\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n = t$ for some $t \in X$.

Definition 2.6 (Aamri [1]). Two self mappings S and T of a metric space (X, d) will be non compatible if there exists at least one sequence $\{x_n\}$ in X such that $\lim_{n \rightarrow \infty} d(ST_{x_n}, TS_{x_n})$ is either nonzero or non-existent.

Remark 2.7. Two noncompatible self mappings of a metric space (X, d) satisfy the property (E.A).

Aamri [1] proved the following theorems.

Theorem 2.8. Let S and T be two weakly compatible selfmappings of a metric space (X, d) such that (i) T and S satisfy the property (E.A), (ii) $d(Tx, Ty) < \text{Max}\{d(Sx, Sy), [d(Tx, Sx) + d(Ty, Sy)]/2, [d(Ty, Sx) + d(Tx, Sy)]/2\} \forall x \neq y \in X$, (iii) $TX \subset SX$. If SX or TX is a complete subspace of X , then T and S have a unique common fixed point.

III. Main Results

In this section we prove common fixed point theorem for sequence of mappings that generalizes Theorem 2.8.

Theorem 3.1 Suppose that $\{A_i\}, \{T_i\}$ be two weakly compatible self mappings of a metric space (X, d) such that (1) For every i , $A_iX \subset T_iX$ (2) A_i and T_i satisfies the property (E.A).

(3) $d(A_i x, A_i y) < \text{Max}\{d(T_i x, T_i y), [d(A_i x, T_i x) + d(A_i y, T_i y)]/2, [d(A_i x, T_i y) + d(A_i y, T_i x)]/2\}$ for every $x \neq y \in X$ and for every i . If $T_i X$ or $S_i X$ is a complete subspace of X , then A_i and T_i have a unique common fixed point.

Proof: Suppose that A_i and T_i satisfies the property (E.A) there exists in X a sequence (x_n) satisfying $\lim_{n \rightarrow \infty} A_i x_n = \lim_{n \rightarrow \infty} T_i x_n = t$ for some $t \in X$, for every i .

Suppose that $T_i X$ is complete. Then $\lim_{n \rightarrow \infty} T_i x_n = T_i a$ for some $a \in X$.

Also $\lim_{n \rightarrow \infty} A_i x_n = T_i a$. We show that $A_i a = T_i a$.

Suppose that $A_i a \neq T_i a$. Condition (3) implies

$$d(A_i x_n, A_i a) < \text{Max}\{d(T_i x_n, T_i a), [d(A_i x_n, T_i x_n) + d(A_i a, T_i a)]/2, [d(A_i x_n, T_i a) + d(A_i a, T_i x_n)]/2\}$$

Letting $n \rightarrow +\infty$ yields.

$d(T_i a, A_i a) < \text{Max} \{d(T_i a, T_i a), [d(T_i a, T_i a) + [d(A_i a, T_i a)]/2, [d(T_i a, T_i a) + [d(A_i a, T_i a)]/2]\} = d(A_i a, T_i a)/2$. Which is a contradiction. Hence $A_i a = T_i a$ for every i .

Since A_i and T_i are weakly compatible, $A_i T_i a = T_i A_i a$ and therefore $A_i A_i a = A_i T_i a = T_i A_i a = T_i T_i a$. $\forall i, i=1, 2, \dots, n$.

Finally, we show that $A_i a$ is a Common fixed point of A_i and $T_i \forall i, i=1, 2, \dots, n$.

Suppose that $A_i a \neq A_i A_i a$. Then we have, $d(A_i a, A_i A_i a) \leq \text{Max} \{ d(T_i a, T_i A_i a), [d(A_i a, T_i a) + d(A_i A_i a, T_i A_i a)]/2, [d(T_i A_i a, A_i a) + d(T_i a, A_i A_i a)]/2 \} \forall i$,

$= \text{Max} \{ d(A_i a, A_i A_i a), 0, [d(A_i a, A_i A_i a) + d(A_i a, A_i A_i a)]/2 \}$

$= \text{Max} \{ d(A_i a, A_i A_i a), d(A_i A_i a, A_i a) \} = d(A_i a, A_i A_i a)$

Therefore $d(A_i A_i a, A_i a) < d(A_i A_i a, A_i a)$ Which is a contradiction. Hence $A_i A_i a = A_i a \forall i$, and $T_i A_i a = A_i A_i a = A_i a$.

The proof is similar when $A_i X$ is assumed to be a complete subspace of X . Since $A_i X \subset T_i X \forall i$.

Uniqueness: Suppose u, v are two fixed points A_i and $T_i \forall i$.

Then $A_i u = T_i u = u \forall i$ and $A_i v = T_i v = v \forall i$

$d(u, v) = d(A_i u, A_i v) < \text{Max} \{d(T_i u, T_i v), [d(A_i u, T_i u) + d(A_i v, T_i v)]/2, [d(A_i u, T_i v) + d(A_i v, T_i u)]/2 \} \forall i$.

$= \text{Max} \{d(u, v), [d(u, u) + d(v, v)]/2, [d(v, u) + d(u, v)]/2 \}$

$= \text{Max} \{d(u, v), 0, d(u, v)\} = d(u, v)$

Therefore, $d(u, v) < d(u, v) \Rightarrow \Leftarrow$ when $u \neq v$. Hence $u = v$.

Therefore A_i and T_i have unique common fixed point for all i .

Now we give an example to support our result.

Example for theorem 3.1: Let $X = [1, \infty)$ with the usual metric $d(x, y) = |x - y|$.

Define $A_i, T_i : X \rightarrow X \forall i$ by $A_i x = 3x - 1$ and $T_i x = x^2 + 1 \forall x \in X$ and $\forall i$

Then (1) A_i and T_i satisfy the property (E.A) for the sequence $x_n = 2 + 2/n, n=1, 2, \dots, n$

For, to prove if $\lim_{n \rightarrow \infty} A_i x_n = \lim_{n \rightarrow \infty} T_i x_n = t$ for some $t \in X$.

$\lim_{n \rightarrow \infty} A_i x_n = \lim_{n \rightarrow \infty} 3x_n - 1 = \lim_{n \rightarrow \infty} 3(2 + 2/n) - 1 = 6 - 1 = 5 \forall i$ -----(i)

and $\lim_{n \rightarrow \infty} T_i x_n = \lim_{n \rightarrow \infty} x_n^2 + 1 = \lim_{n \rightarrow \infty} (2 + 2/n)^2 + 1 = 4 + 1 = 5 \forall i$ -----(ii)

From (i) and (ii) we get A_i and $T_i \forall i$ satisfy the property (E.A).

(2) T_i and $A_i \forall i$ are weakly compatible. (3) A_i and T_i satisfy for all $x \neq y, \forall i$

$d(A_i x, A_i y) < \text{Max} \{d(T_i x, T_i y), [d(A_i x, T_i x) + d(A_i y, T_i y)]/2, [d(A_i x, T_i y) + d(A_i y, T_i x)]/2 \}$

for all $x \neq y, \forall i$

(4) $T_i 1 = A_i 1 = 2$. For, $T_i 1 = 1^2 + 1 = 2$ and $A_i 1 = 3(1) - 1 = 2$.

Theorem 3.2. Let A_i, B_i, T_i and S_i be self maps of a metric space (X, d) such that

(1) $A_i X \subset T_i X$ and $B_i X \subset S_i X$ for every i . (2) $(A_i, S_i), \forall i$ is weakly compatible.

(3) (A_i, S_i) or $(B_i, T_i), \forall i$ satisfies the property (E.A).

(4) $d(A_i x, B_i y) < \text{Max} \{d(S_i x, T_i y), d(A_i x, S_i x), d(B_i y, T_i y), [d(S_i x, B_i y) + d(A_i x, T_i y)]/2 \} \forall i$

If the range of the one of the mappings A_i, B_i, S_i or $T_i \forall i$ is a complete subspace of X ,

Then (I) A_i and $S_i \forall i$ have a common fixed point. (II) $B_i, T_i \forall i$ have a common fixed point provided that $(B_k, T_i) \forall i$ for every k is weakly compatible.

(III) A_i, B_i, S_i and $T_i \forall i$ have a unique common fixed point provided that (I) and (II) are true.

Proof: Suppose that $(B_i, T_i) \forall i$ satisfies the property (E.A) \Rightarrow There exists a sequence $\{x_n\}$ in X such that $\lim_{n \rightarrow \infty} B_i x_n = \lim_{n \rightarrow \infty} T_i x_n = t$ for some $t \in X$ for every i .

Since, $B_i X \subset S_i X \forall i$, there exists a sequence $\{y_n\}$ in X such that $B_i x_n = S_i y_n$.

Therefore $\lim_{n \rightarrow \infty} B_i x_n = \lim_{n \rightarrow \infty} S_i y_n = t$ (Since, $\lim_{n \rightarrow \infty} B_i x_n = t$)

Let us prove that $\lim_{n \rightarrow \infty} A_i y_n = t$.

It is enough to prove that $A_i y_n = B_i x_n \forall i$, and for sufficiently large n .

Suppose not, then using (4), $d(A_i y_n, B_i x_n) < \text{Max} \{d(S_i y_n, T_i x_n), d(A_i y_n, S_i y_n), d(B_i x_n, T_i x_n), [d(S_i y_n, B_i x_n)$

$+ d(A_i y_n, T_i x_n)]/2 \} \forall i = \text{Max} \{ d(B_i x_n, T_i x_n), d(A_i y_n, B_i x_n), d(B_i x_n, T_i x_n),$

$[d(B_i x_n, B_i x_n) + d(A_i y_n, B_i x_n)]/2 \} \forall i$

For sufficiently large n , $d(A_i y_n, B_i x_n) < \text{Max} \{d(A_i y_n, B_i x_n), 1/2 d(A_i y_n, B_i x_n)\},$

$< d(A_i y_n, B_i x_n)$

$\Rightarrow \Leftarrow$ when $A_i y_n \neq B_i x_n \forall i$

Therefore $A_i y_n = B_i x_n$ as $n \rightarrow \infty \forall i$

Therefore $\lim_{n \rightarrow \infty} A_i y_n = t. \forall i$ (Since, $\lim_{n \rightarrow \infty} B_i x_n = t. \forall i$)

Suppose, $S_i X \forall i$ is a complete subspace of X .

$\Rightarrow t = S_i u \forall i$ for some $u \in X$.

Therefore $\lim_{n \rightarrow \infty} A_i y_n = \lim_{n \rightarrow \infty} B_i x_n = \lim_{n \rightarrow \infty} T_i x_n = \lim_{n \rightarrow \infty} S_i y_n = S_i u \forall i$

$$d(A_i u, B_i x_n) < \text{Max} \{d(S_i u, T_i x_n), d(A_i u, S_i u), d(B_i x_n, T_i x_n), [d(S_i u, B_i x_n) + d(A_i u, T_i x_n)]/2\} \forall i.$$

For sufficiently large n , $d(A_i u, B_i x_n) < \text{Max} \{d(A_i u, S_i u), 1/2d(A_i u, S_i u)\} \forall i$

$$d(A_i u, S_i u) < d(A_i u, S_i u) \forall i$$

$\Rightarrow \Leftarrow$ when $A_i u \neq S_i u \forall i$.

Therefore $A_i u = S_i u \forall i$. This means that A_i and $S_i \forall i$ have coincidence point.

But $(A_i, S_i) \forall i$ is weakly compatible. Therefore $S_i A_i u = A_i S_i u$ for every i and then $A_i A_i u = A_i S_i u = S_i A_i u = S_i S_i u$ for every i

Suppose $A_i X \subset T_i X$ for every i

\Rightarrow There exists $v \in X$ such that $A_i u = T_i v \forall i \Rightarrow A_i u = S_i u = T_i v \forall i$

To prove that $T_i v = B_i v, \forall i$

Suppose $B_i v \neq T_i v, \forall i$, then $d(A_i u, B_i v) < \text{Max} \{d(S_i u, T_i v), d(A_i u, S_i u), d(B_i v, T_i v), [d(S_i u, B_i v) +$

$$d(A_i u, T_i v)]/2\} \forall i = \text{Max} \{d(T_i v, T_i v), d(S_i u, S_i u), d(B_i v, T_i v), [d(T_i v, B_i v) + d(T_i v, T_i v)]/2\} \forall i.$$

$$= \text{Max} \{d(B_i v, T_i v), d(B_i v, T_i v)/2\} \forall i = d(B_i v, T_i v) \forall i = d(B_i v, A_i u) \forall i$$

$$\text{Therefore } d(A_i u, B_i v) < d(A_i u, B_i v) \forall i \Rightarrow \Leftarrow =$$

Therefore $A_i u = B_i v \forall i$

$$\Rightarrow B_i v = A_i u = T_i v \forall i$$

Therefore $B_i v = T_i v \forall i$

$$\Rightarrow A_i u = S_i u = T_i v = B_i v \forall i$$

But $(B_k, T_k) \forall k$ is weakly compatible and for some $k > 1$

$$B_k T_i v = T_i B_k v \text{ for some } k > 1 \forall i$$

And $T_i T_i v = T_i B_k v = B_k T_i v = B_k B_k v$ for some $k > 1$ and $\forall i$

We shall prove that $A_i u$ is a common fixed point of A_i and $S_i \forall i$

Suppose $A_i u \neq A_i A_i u \forall i$

$$d(A_i u, A_i A_i u) = d(A_i A_i u, B_i v) \forall i \quad (\text{Since, } A_i u = B_i v \forall i)$$

$$< \text{Max} \{d(S_i A_i u, T_i v), d(A_i A_i u, S_i A_i u), d(B_i v, T_i v), [d(S_i A_i u, B_i v) + d(A_i A_i u, T_i v)]/2\} \forall i.$$

$$= \text{Max} \{d(A_i A_i u, B_i v), 0, 0, 1/2[d(A_i A_i u, B_i v) + d(A_i A_i u, B_i v)]\}$$

$$= d(A_i A_i u, B_i v) \forall i$$

$$\text{Therefore } d(A_i A_i u, B_i v) < d(A_i A_i u, B_i v) \forall i$$

$$\Rightarrow \Leftarrow =$$

Therefore $A_i A_i u = B_i v \forall i \Rightarrow A_i A_i u = A_i u = S_i A_i u \forall i$ (Since, $A_i A_i u = S_i A_i u \forall i$)

$\Rightarrow A_i u$ is a common fixed point of A_i and $S_i \forall i$

This proves (I).

To prove that $B_k v = A_i u$ for some $k > 1$, is a common fixed point of B_i and $T_i \forall i$

Suppose $B_k v \neq B_i B_k v, d(B_k v, B_i B_k v) = d(A_i u, B_i B_k v) < \text{Max} \{d(S_i u, T_i B_k v), d(A_i u, S_i u), d(B_i B_k v, T_i B_k v), [d(S_i u, B_i B_k v) + d(A_i u, T_i B_k v)]/2\} \forall i$

$$= \text{Max} \{d(A_i u, B_i B_k v), 0, d(B_i B_k v, B_i B_k v), [d(A_i u, B_i B_k v) + d(A_i u, B_i B_k v)]/2\} \forall i$$

$$= \text{Max} \{d(A_i u, B_i B_k v), 0, 0, d(A_i u, B_i B_k v)\} \forall i$$

$$\text{Therefore } d(B_k v, B_i B_k v) < d(A_i u, B_i B_k v) \forall i$$

$$\Rightarrow \Leftarrow = (\text{Since, } B_k v = A_i u)$$

Therefore $A_i u = B_i B_k v$ That is, $B_k v = B_i B_k v = T_i B_k v$ (Since, $B_i v = T_i v$)

$\Rightarrow B_k v$ is the common fixed point of B_i and $T_i \forall i$. This proves (II)

Now, $A_i u$ is a common fixed point of A_i and $S_i \forall i$

$B_k v = A_i u$ is a common fixed point of B_i and $T_i \forall i$

Therefore, $A_i u$ is the common fixed point of B_i, T_i and S_i for all i

The proof is similar when $T_i X$ is assumed to be a complete subspace of X .

The cases in which $A_i X$ or $B_i X \forall i$ is a complete subspace of X are similar to the cases in which $S_i X$ or $T_i X$ respectively is a complete space because $A_i X \subset T_i X$ and $B_i X \subset S_i X$ for every i .

Uniqueness: Suppose u, v are fixed points of A_i, B_i, T_i and S_i for every i .

Then $A_i u = S_i u = B_i u = T_i u = u \forall i$ and $A_i v = B_i v = T_i v = S_i v = v$ for every i .

$$d(u, v) = d(A_i u, B_i v) \text{ for every } i.$$

$$< \text{Max} \{d(S_i u, T_i v), d(A_i u, S_i u), d(B_i v, T_i v), 1/2[d(S_i u, B_i v) + d(A_i u, T_i v)]\}$$

$$= \text{Max} \{d(u, v), 0, 0, 1/2[d(u, v) + d(u, v)]\} = \text{Max} \{d(u, v), d(u, v)\}$$

$$d(u, v) < d(u, v). \Rightarrow \Leftarrow = \text{when } u \neq v.$$

Therefore $u = v$. Hence A_i, B_i, S_i and $T_i \forall i$ have a unique common fixed point.

The following result due to U.Karupiah [2] is a special case of the previous theorem 3.2.

Corollary 3.2: Let $\{A_i\}$, S and T be self maps of a metric space (X, d) such that

(1) $A_i X \subset T X$ and $A_i X \subset S X$ for $i > 1$.

(2) (A_1, S) is weakly compatible.

(3) (A_i, S) or (A_i, T) , $i > 1$ satisfies the property (E.A).

(4) $d(A_1x, A_1y) < \max \{d(S_x, T_y), d(A_1x, S_x), d(A_1y, T_y), d(A_1x, T_y), d(A_1y, S_x)\}$ for $i > 1$.

If the range of the one of the mappings $\{A_i\}$, S or T is a complete subspace of X , then

(I) A_1 and S have a common fixed point. (II) A_i , $i > 1$ and T have a common fixed point provided that (A_k, T) for some $k > 1$ is weakly compatible.

(III) A_i , S and T have a unique common fixed point provided that (I) and (II) are true.

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